Simultaneous brain tumor and organs-at-risk segmentation for radiotherapy

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Introduction

When planning for radiotherapy of brain tumors several structures need to be segmented from MR images, such as tumors and socalled organs-at-risk (structures to be spared from radiation). Automatic segmentation is challenging since tumor location, shape, appearance and effect on healthy tissue vary greatly across patients. Moreover, MR intensi-



Fig 1: MR slices of a subject: Expert segmentation, Flair, T2, T1 with contrast and automatic segmentation. Automatic segmentation: Healthy labels **l** in dark blue, orange and green. Complete tumor label \mathbf{z} in lilac and yellow. Core label \mathbf{y} in yellow, existing inside \mathbf{z} .

ties can vary significantly across scanners.

We propose a fully automated generative method for simultaneous segmentation of brain tumors and organs-at-risk (see fig. 2), We combine an existing whole-brain segmentation technique [1] with a spatial tumor prior, using convolutional restricted Boltzmann machines (cRBMs). The cRBMs are trained on expert tumor segmentations, without the use of any intensity information.

Model

RBM tumor shape prior

• A convolutional restricted Boltzmann machine is a graphical model over visible and hidden units [2]. The visible and hidden layers are connected through convolutional



Graphical representation of model.

• Bias fields corrupting the MR images are modeled as linear combinations of spatially smooth basis functions, with parameters in $\boldsymbol{\theta}$.

Healthy tissue prior

Experiments

- Each RBM was trained with 40 filters (size 7x7x7) on expert segmentations of 30 subjects for 9600 gradient steps of 0.1 with CD-1 and enhanced gradient [4].
- The method has been tested on 20 patients that have undergone radiotherapy treatment at Rigshospitalet.





- We separately train one cRBM for the complete tumor label \mathbf{z} , with hidden units in **H**, and one RBM for tumor core label \mathbf{y} , with hidden units **G**.
- After training, the two cRBMs are combined to form a combined prior on tumor shape:

 $p(\mathbf{z},\mathbf{y}) \propto \sum_{\mathbf{H},\mathbf{G}} \exp(-E_z(\mathbf{z},\mathbf{H}) - E_y(\mathbf{y},\mathbf{G}) - f(\mathbf{y},\mathbf{z})),$

where $f(\mathbf{y}, \mathbf{z})$ insures that core only exist within complete tumor and E denotes the cRBM energy term.

Likelihood function

For the prior on the healthy tissue labels in ${f l}$ we use a deformable probabilistic atlas computed from healthy subjects, consisting of mesh nodes η [3]. The healthy prior is given by

 $p(\mathbf{l}) = \int_{\mathbf{n}}^{\mathbf{r}} p(\mathbf{l} | \mathbf{\eta}) p(\mathbf{\eta}) d\mathbf{\eta}$ and

 $p(\mathbf{l}|\mathbf{\eta}) = \prod_{i} p(l_i | \mathbf{\eta}).$

Inference

- Step 1: Use $p(\mathbf{l}, \mathbf{z}, \mathbf{y} | \mathbf{D}) \simeq p(\mathbf{l}, \mathbf{z}, \mathbf{y} | \mathbf{D}, \widehat{\mathbf{\theta}}, \widehat{\mathbf{\eta}})$, where $\langle \widehat{\theta}, \widehat{\eta} \rangle$ maximize $p(\theta, \eta | \mathbf{D})$.
 - Alternate between optimizing $\boldsymbol{\theta}$ by generalized Expectation-Maximization while keeping fixed η , and η by conjugate gradient while keeping θ fixed.
 - RBM energy temporarily replaced in this step with a simpler factorizable energy term.





Fig 4: Automatic segmentation after step 1 on the left and final segmentation on the right.



Fig 5: Brainstem segmentation. Manual in green, automatic in red. Note the difference in protocol.



• The likelihood function links labels to MR intensities in data **D**. Each label is connected to a Gaussian mixture model with model parameters in $\boldsymbol{\theta}$. The likelihood is given by

 $p(\mathbf{D} | \mathbf{l}, \mathbf{z}, \mathbf{y}) = \int_{\mathbf{\theta}} p(\mathbf{D} | \mathbf{l}, \mathbf{z}, \mathbf{y}, \mathbf{\theta}) p(\mathbf{\theta}) d\mathbf{\theta}.$

References

- [1] Puonti, O., et al.: Fast, Sequence Adaptive Parcellation of Brain MR Using Parametric Models. In: Proc. MICCAI 2013. (2013) [2]Lee, H., et al.: Convolutional deep belief networks for scalable unsupervised learning of hierarchical representations. In: Proceedings of the 26th Annual International Conference on Machine Learning, ACM (2009) [3] Van Leemput, K.: Encoding Probabilistic Brain Atlases Using Bayesian Inference. IEEE Trans Med Imag 28(6), (2009)
- [4] Melchior, J., et al.: How to Center Binary Restricted Boltzmann Machines. arXiv preprint arXiv:1311.1354 (2013)

- Step 2: Monte Carlo sampling from $p(\mathbf{l}, \mathbf{z}, \mathbf{y} | \mathbf{D}, \widehat{\mathbf{\eta}})$, with $\mathbf{\eta}$ kept fixed. • Initialize with $\widehat{\boldsymbol{\theta}}$.
 - Block-Gibbs sampling from $p(\mathbf{l}, \mathbf{z}, \mathbf{y}, \mathbf{H}, \mathbf{G}, \boldsymbol{\theta} | \mathbf{D}, \widehat{\boldsymbol{\eta}})$, only retaining samples of **l**, **z** and **y**.

Fig 6: Hippocampus segmentations. Note that manual labels are less precise.